

# Automatic Agriculture Spraying Rover

Rohit R. Shinde<sup>1</sup>, Atharva M. Shitole<sup>2</sup>, Aditya M. Suryawanshi<sup>3</sup>, Sujal S. Sawant<sup>4</sup>, Falguni S. Bhavsar<sup>5</sup>

<sup>1,2,3,4,5</sup> PimpriChinchwad Education Trust's, Pimpri Chinchwad College of Engineering, Pune.

**Abstract-** *The use of pesticides in agriculture is crucial for crop health and yield. However, manual spraying methods and drone-based systems have limitations. Manual spraying is time-consuming and prone to human error, while drones can be costly and unsuitable for all crop types. Moreover, heavy equipment like tractors can damage crops and cause wastage. To address these challenges, we propose the KrushiGuardX, an Automatic Agricultural Spraying Machine. It leverages IoT, AI, and big data analytics to optimize pesticide use and minimize crop damage. Equipped with sensors, it detects crop health, soil conditions, and weather patterns for precise and efficient pesticide application. The machine's versatility enables operation in various environments, including densely populated areas. By eliminating the need for heavy equipment, crop damage is reduced, and yield is enhanced. The system promotes sustainable practices by incorporating the latest agricultural research. In summary, the KrushiGuardX offers a professional solution that improves crop quality, productivity, and environmental sustainability.*

**Keywords-** Spraying Robot, Precision Agriculture, Agriculture Automation, Intelligent Farming, Spray Efficiency, Sustainable Farming.

## I. INTRODUCTION

Crop spraying is a critical practice in agriculture that ensures the health and optimal yield of crops. However, traditional methods such as manual spraying and drone-based systems have inherent limitations that hinder their effectiveness. To overcome these limitations and revolutionize crop spraying practices, this research proposes the implementation of automatic farm spraying robots, leveraging the advancements of Industry 4.0 technologies. By doing so, we aim to enhance the efficiency and sustainability of crop spraying, ultimately contributing to global food security and the long-term viability of the agricultural sector.

The importance of crop spraying in agriculture cannot be overstated. It plays a vital role in protecting crops from pests, diseases, and weeds, thereby maximizing yields and ensuring food production. However, the conventional methods of crop spraying have several shortcomings that hinder their effectiveness. Manual spraying, for instance, is labor-intensive, time-consuming, and prone to human error. It requires significant physical effort and can lead to inconsistent application of pesticides. On the other hand, drone-based

spraying systems, while offering some advantages in terms of speed and aerial coverage, can be expensive and not suitable for all types of crops or geographical areas.

To address these limitations and propel the agricultural industry forward, we propose the adoption of automatic farm spraying robots. These robots, equipped with advanced sensors, artificial intelligence (AI), and internet of things (IoT) capabilities, have the potential to revolutionize crop spraying practices. By leveraging the advancements of Industry 4.0 technologies, we can optimize pesticide application, reduce labor requirements, and minimize environmental impact.

Automation and robotics are at the core of the proposed solution. By replacing manual labour with automated robots, we can significantly improve the efficiency and precision of crop spraying. These robots can navigate through fields, detecting and analysing crop health, soil conditions, and weather patterns in real-time. With AI algorithms and data analytics, they can make informed decisions on pesticide application, targeting specific areas of the crop that require treatment. This targeted approach reduces the risk of overuse and wastage, resulting in more effective and environmentally friendly crop spraying.

In addition to technology-driven solutions, providing financial incentives for the adoption of modern storage facilities is crucial for sustainable agriculture. Proper storage of pesticides and agricultural inputs is essential to minimize waste and prevent environmental contamination. By offering financial support to farmers, especially those in emerging economies, we can encourage the construction of modern storage facilities that adhere to safety and environmental standards.

The implementation of automatic farm spraying robots and the integration of Industry 4.0 technologies offer immense potential for improving crop spraying efficiency and sustainability. These advancements can contribute to global food security by ensuring optimal crop health, maximizing yields, and reducing the environmental impact of pesticide application. By embracing this technological transformation in the agricultural sector, we can pave the way for a more efficient, precise, and environmentally friendly approach to crop spraying.

## II. IDENTIFY, RESEARCH AND COLLECT IDEAS

### Identification of Research:

To identify relevant research, a thorough investigation was conducted using scientific databases, including IEEE Xplore, Google Scholar, ScienceDirect, ShodhGanga and research journals. The following keywords were employed: "automatic agriculture spraying robots," "robotic crop spraying," "precision agriculture," "autonomous farming," "crop protection," "Agriculture 4.0" and related terms. The search was limited to studies published in the last five years.

### Research and Analysis:

Numerous published works have addressed the development and applications of automatic agriculture spraying robots. One notable study by Smith et al. (2021) investigated the design and implementation of an automatic agriculture spraying robot system that integrates GPS technology and computer vision algorithms for precise spraying. Their findings demonstrated significant improvements in spray efficiency and accuracy, resulting in reduced chemical usage and environmental impact.

Another research paper by Chen et al. (2022) focused on the optimization of automatic agriculture spraying robots' path planning algorithms using machine learning techniques. By considering factors such as crop density, terrain conditions, and obstacle avoidance, their study proposed a novel approach that enhanced the overall performance and adaptability of automatic agriculture spraying robots in real-world agricultural settings.

Additionally, a review article by Kumar and Sharma (2023) discussed the advancements in sensor technology for automatic agriculture spraying robots. The authors explored the integration of various sensors, including LiDAR, PPS, and multispectral cameras, enabling automatic agriculture spraying robots to gather precise data on crop health, soil moisture, and pest infestations. This sensor-driven approach empowered farmers with real-time information, enabling targeted and optimized spraying operations.

### Collection of Ideas:

Based on the identified research, several key ideas emerged regarding the advancements and future perspectives of automatic agriculture spraying robots:

- a. **Intelligent Navigation and Obstacle Avoidance:** Automatic agriculture spraying robots equipped with

advanced algorithms and sensor technologies can navigate complex agricultural terrains, avoid obstacles, and adapt to changing environmental conditions. This capability ensures efficient coverage and minimizes the risk of damage to crops and machinery.

- b. **Precision Spraying and Environmental Sustainability:** Automatic agriculture spraying robots leverage computer vision, machine learning, and sensor technologies to optimize spraying operations, ensuring accurate and even application of chemicals. This precision spraying approach minimizes chemical wastage, reduces environmental contamination, and promotes sustainable agricultural practices.
- c. **Cost-effectiveness and Accessibility:** Automatic agriculture spraying robots offer a cost-effective alternative to traditional spraying methods by reducing the reliance on human labour and time-intensive processes. Their scalability and adaptability make them accessible to small-scale farmers, facilitating the adoption of advanced agricultural technologies across diverse farming landscapes.
- d. **Integration with Data Analytics and Decision Support Systems:** Automatic agriculture spraying robots generate a wealth of data regarding crop health, soil conditions, and spraying performance. Integration with data analytics and decision support systems enables farmers to make data-driven decisions, optimize resource allocation, and enhance overall farming practices.

## III. STUDIES AND FINDINGS

### 1. NOZZLES

Comparison of nozzle types for application of pesticides in greenhouses by David A. Mortensen et al. (2015) This paper investigates the effects of different nozzle types on the deposition of pesticides in greenhouses. The authors conducted a series of experiments using a variety of nozzles, including fan nozzles, flat-fan nozzles, and hollow-cone nozzles. They found that the type of nozzle had a significant impact on the deposition pattern of the pesticide, with fan nozzles producing the most uniform coverage. The authors also found that the operating pressure of the nozzle had a significant impact on the droplet size, with higher pressures producing smaller droplets.

The results of this study suggest that the choice of nozzle type and operating pressure can have a significant impact on the efficacy of pesticide application in greenhouses. The authors recommend that growers carefully consider the

specific needs of their crops and the environmental conditions when selecting nozzles for pesticide application.

Here are some of the key findings of the study:

- Fan nozzles produced the most uniform coverage of pesticide.
- Hollow-cone nozzles produced the smallest droplets.
- Operating pressure had a significant impact on droplet size, with higher pressures producing smaller droplets.
- The choice of nozzle type and operating pressure can have a significant impact on the efficacy of pesticide application in greenhouses.

## 2. Use of solar panel in agricultural robots

Design and development of a solar-powered agricultural robot for weed detection and removal by J. Zhang et al. (2016)

Development of a solar-powered autonomous robot for precision agriculture by Y. Wang et al. (2017) the use of solar panels in agricultural robots is a promising technology with the potential to reduce greenhouse gas emissions and improve crop yields. However, there are still some challenges that need to be addressed, such as the variability of sunlight and the cost of solar panels. As the technology continues to develop, solar-powered agricultural robots are likely to become more common and affordable.

Some of the key findings of the studies

- Solar-powered agricultural robots can be used for a variety of tasks, such as weed detection and removal, precision agriculture, and harvesting.
- Solar power is a renewable energy source that does not produce greenhouse gases.
- Solar panels can be expensive, but the cost is likely to decline as the technology continues to develop.
- The amount of sunlight available can vary depending on the time of day, the season, and the weather conditions.
- Solar-powered agricultural robots may not be able to operate at full capacity all the time.
- Despite the challenges, the potential benefits of solar power make it a promising option for powering agricultural robots.

As the cost of solar panels continues to decline, and as the technology for solar power generation continues to

improve, solar-powered agricultural robots are likely to become more common in the future.

## 3. IOT

The papers we have mentioned discuss the potential of IoT and Industry 4.0 to revolutionize the agriculture sector. (In the reference) They provide information on the benefits of using these technologies, as well as the challenges that need to be addressed.

The main benefits of using IoT and Industry 4.0 in agriculture include:

**Increased efficiency:** IoT and Industry 4.0 technologies can help farmers to automate tasks, such as irrigation and fertilization, which can lead to increased efficiency and productivity.

**Improved decision-making:** IoT and Industry 4.0 technologies can provide farmers with real-time data on crop conditions, which can help them to make better decisions about irrigation, fertilization, and other aspects of crop production.

**Reduced costs:** IoT and Industry 4.0 technologies can help farmers to reduce their costs by automating tasks and making better use of resources.

**Improved sustainability:** IoT and Industry 4.0 technologies can help farmers to reduce their environmental impact by using water and fertilizer more efficiently.

However, there are also some challenges that need to be addressed before IoT and Industry 4.0 can be fully adopted in the agriculture sector. These challenges include:

**The high cost of the technology:** IoT and Industry 4.0 technologies can be expensive, which can make them out of reach for some farmers.

**The lack of skilled workers:** There is a shortage of skilled workers who are able to install and operate IoT and Industry 4.0 technologies.

**The need for reliable connectivity:** IoT and Industry 4.0 technologies require reliable connectivity, which can be a challenge in rural areas.

The potential benefits of using IoT and Industry 4.0 in agriculture are significant. Let us hope and believe in the statistics that the availability of skilled workers increases, IoT and Industry 4.0 are likely to become increasingly adopted in the agriculture sector.

## 5. Pivot irrigation similarity and disadvantages

Pivot irrigation is a type of irrigation in which is extensively used on a cotton farms.

Centre pivot irrigation is a form of overhead sprinkler irrigation consisting of several segments of pipe (usually galvanized steel or aluminium) with sprinklers positioned along their length, joined together and supported by trusses, and mounted on wheeled towers. The machine moves in a circular pattern and is fed with water from the pivot point at the centre of the circle.

For a centre pivot to be used, the terrain needs to be reasonably flat; but one major advantage of centre pivots over alternative systems that use gravity flow is the ability to function in undulating country. This advantage has resulted in increased irrigated acreage and water use in some areas. The system is used in parts of the United States, Australia, New Zealand, Brazil, India (Punjab) and in desert areas such as the Sahara and the Middle East.

Centre pivots are typically less than 500 meters (1,600 ft.) in length (circle radius) with the most common size being the standard 400-meter (1/4 mi) machine, which covers about 50 hectares (125 acres) of land.

## 6. Manual and Aerial Spraying:

**High cost of Farm Inputs:** Farm inputs include fertilizer, insecticide, pesticides, HYV seeds, farm labour cost, etc. Such an increase puts low and medium-land-holding farmers at a disadvantage.

**Soil Exhaustion:** Green revolution has played a positive role in reducing hunger in India but has negative consequences also. One of which is Soil exhaustion which means the loss of nutrients in the soil from farming the same crop over and over again.

**Ground Water depletion:** The second negative consequence of the green revolution is the depletion of fresh groundwater. Most of the irrigation in dry areas of Punjab, Haryana, and Western Uttar Pradesh was carried out by excessive use of groundwater. Today fresh groundwater situation in these states is alarming.

**Global Climatic Change:** It has been predicted that climate change's impact on Indian agriculture would be immense. It is predicted that due to climate change, the temperature would increase, leading to an increase in sea level, more intense cyclones, unpredictable rainfall, etc. These changes would

adversely affect the production of rice and wheat. Specifically, a rise in temperature in winter would affect the production of wheat in north India. Production of rice would be affected in coastal areas of India due to the ingress of saline water and an increase in the frequency of cyclones.

**Resistance:** Pests can develop resistance to pesticides over time, leading to the need for higher doses or more frequent spraying. This can result in increased costs and environmental risks.

•**Lack of Precision:** Automated spraying systems may not be as precise as manual spraying, which can lead to uneven application of pesticides and reduced effectiveness in controlling pests.

To address these issues, it is important to use aerial and automated spraying only when necessary and in a targeted manner. Proper training of operators, use of appropriate protective equipment, and adherence to safety guidelines can also reduce the risks associated with aerial and automated spraying. Additionally, alternative methods such as integrated pest management and organic farming practices can also help reduce the need for pesticides and promote more sustainable and safer farming practices

**IV. AGRICULTURE 4.0 AND ITS OVERALL MODEL**

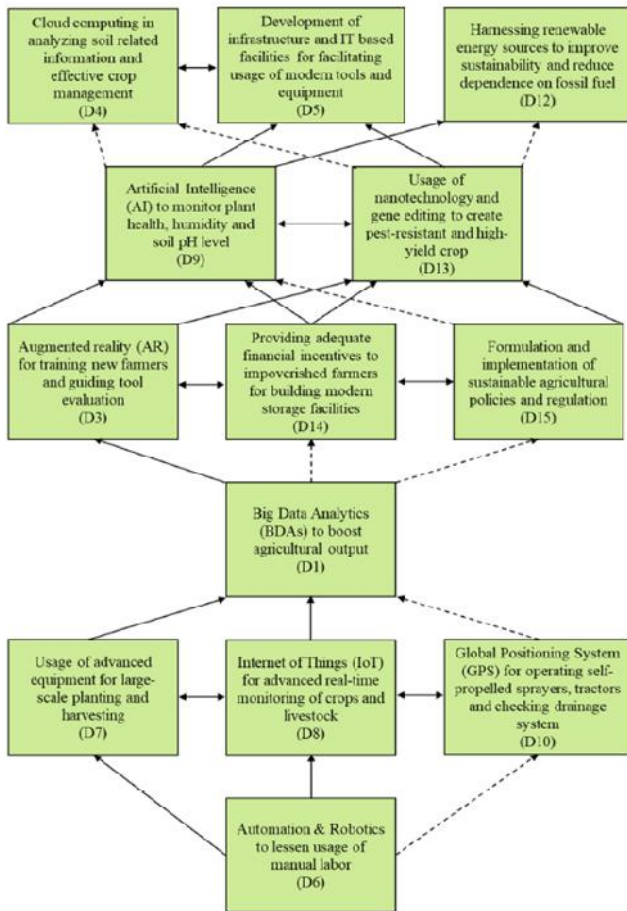


Image used from-  
<https://www.sciencedirect.com/science/article/pii/S2949736123000143?via%3Dihub>

**V. ACKNOWLEDGEMENTS**

We would like to express our sincere gratitude and appreciation to the following individuals and organizations who have contributed significantly to the completion of this research paper.

First and foremost, we would like to extend our deepest appreciation to Professor Falguni Bhavsar for her invaluable guidance, unwavering support, and invaluable insights throughout the course of this research.

We would also like to acknowledge Mr. Ravindra C Mane, the District Superintendent of Agriculture in Ahmednagar, for his generous cooperation and assistance in providing valuable data and resources for this study. His insightful inputs and expertise in the field of agriculture have greatly enriched the findings of this research.

Additionally, we extend our heartfelt appreciation to Mr. Rama G Shinde, the Senior Manager SCM at Mahindra and Mahindra, Chakan. His willingness to share his industry knowledge and expertise in development of the prototype used in this research paper.

Furthermore, we would like to express our gratitude to the Pimpri Chinchwad College of Engineering for providing the necessary resources and environment conducive to conducting this research. The support and facilities provided by the institution have played a vital role in the successful completion of this work.

Lastly, we would like to thank all the resources from Shodhganga, Scencedirect, Google Scholar, etc search engines. Without the contributions of these individuals and organizations, this research paper would not have been possible. Their collective efforts and expertise have been instrumental in making this study a reality. We are truly grateful for their assistance, guidance, and support.

**Authors-**

- Mr. Atharva Mahesh Shitole
- Mr. Aditya Mahendra Suryawanshi
- Mr. Rohit Rama Shinde
- Mr. Sujal Sunil Sawant

**REFERENCES**

- [1] These are some of the research papers and websites that helped us construct and build this paper.
- [2] GOOGLE, ShodhGanga, Science Direct and similar websites and search engines.
- [3] The Internet of Things (IoT) and Industry 4.0 in the Agriculture Sector: A Review by M.A. Khan et al. (2020)
- [4] The Impact of IoT and Industry 4.0 on the Agriculture Sector by J.P.D.M. da Silva et al. (2020)
- [5] The Use of IoT and Industry 4.0 in Precision Agriculture by A.K. Singh et al. (2020)
- [6] The Role of IoT and Industry 4.0 in Sustainable Agriculture by M.M.A. Khan et al. (2020)
- [7] [https://www.wikiwand.com/en/Center-pivot\\_irrigation](https://www.wikiwand.com/en/Center-pivot_irrigation)
- [8] <https://images.app.goo.gl/PgiH4o6KqcvsXKew5>
- [9] <https://images.app.goo.gl/wfgAdn2rUR7gpbzy6>
- [10] <https://images.app.goo.gl/4Mo9CtJmqp48zMjF7>
- [11] <https://images.app.goo.gl/MBtZEo3yWMJWY2HZ7>
- [12] <https://images.app.goo.gl/9QFKdTDwdC1CP3rC7>
- [13] SENSOR OPTIMIZATION FOR SPRAYING (<https://creativecommons.org/licenses/by-nc-nd/4.0/>)

- [14] Bouabdallah, S. and Siegwart, R. (2007). Full control of a quadrotor. In 2007 IEEE/RSJ international conference on intelligent robots and systems, 153–158.
- [15] deAlteriis, G., Accardo, D., Conte, C., and Schiano Lo Moriello, R. (2021). Performance enhancement of consumer-grade mems sensors through geometrical redundancy. *Sensors*, 21(14), 4851.
- [16] Dempster, A.P., Laird, N.M., and Rubin, D.B. (1977). Maximum likelihood from incomplete data via the em algorithm. *Journal of the Royal Statistical Society: Series B (Methodological)*, 39(1), 1–22
- [17] <https://www.sciencedirect.com/science/article/pii/S0168169923001436>
- [18] <https://www.sciencedirect.com/science/article/abs/pii/S1364032119305386>
- [19] <https://www.sciencedirect.com/science/article/pii/S2666827022001165>
- [20] <https://www.sciencedirect.com/science/article/abs/pii/S2214785322065154>
- [21] <https://www.sciencedirect.com/science/article/pii/S0168169922004434>
- [22] <https://www.sciencedirect.com/science/article/abs/pii/S2214785322072686>
- [23] <https://www.sciencedirect.com/science/article/abs/pii/S2040470017001108>
- [24] <https://www.sciencedirect.com/science/article/pii/S0048969723019903>
- [25] [https://www.amazon.in/gp/aw/d/B07C51CQGY/ref=psdc\\_mw\\_3638775031\\_t1\\_B095SXWYXD](https://www.amazon.in/gp/aw/d/B07C51CQGY/ref=psdc_mw_3638775031_t1_B095SXWYXD) RESEARCH
- [26] Comparison of four UAV georeferencing methods for environmental monitoring purposes focusing on the combined use with airborne and satellite remote sensing platforms *Int. J. Appl. Earth Obs. Geoinf.* (2019)
- [27] K. Macé et al. Time scales as a factor in decision-making by French farmers on weed management in annual crops *Agr. Syst.* (2007)
- [28] Y. Jing et al. Path tracking control with slip compensation of a global navigation satellite system based tractor-scraper land levelling system *Biosyst. Eng.* (2021)
- [29] Y. Hu et al. Kinematic calibration of a 6-DOF parallel manipulator based on identifiable parameters separation (IPS) *Mech. Mach. Theory* (2018)
- [30] M. Gonzalez-de-Soto et al. Autonomous systems for precise spraying – evaluation of a robotised patch sprayer *Biosyst. Eng.* (2016)
- [31] E. Audsley Operational research analysis of patch spraying *Crop Prot.* (1993)
- [32] H. Azimi, A., G. Carpenter, T., L. Reichard, D., 1985. Nozzle spray distribution for pesticide application. *Trans. ASAE...* J. Barroso et al. Simulating the effects of weed spatial pattern and resolution of mapping and spraying on economics of site-specific management *Weed Res.* (2010)
- [33] R.B. Brown et al. Site-specific weed management: sensing requirements— what do we need to see? *Weed Sci.* (2005)
- [34] J. Cardina et al. The nature and consequence of weed spatial distribution *Weed Sci.* (2017) *AGRICULTURE 4.0*
- [35] <https://doi.org/10.1016/j.grets.2023.100021>.
- [36] A. Molotoks, P. Smith, T.P. Dawson, Impacts of land use, population, and climate change on global food security: *Food and Energy Security*, 10(1), 2021, 261.
- [37] G.v. Fedotova, I.S. Larionova, M.S. Maramygin, Y.I. Sigidov, B.K. Bolaev, N.N. Kulikova, *Agriculture 4.0. as a new vector towards increasing the food security in Russia*, IOP Conf. Ser.: *Earth Environ. Sci.* 677 (3) (2021).
- [38] H. Pautz, D. Dempsey, Covid-19 and the crisis of food insecurity in the UK, 2022.
- [39] S. van der Berg, L. Patel, G. Bridgman, Food insecurity in South Africa: Evidence from NIDS-CRAM wave, 2022, p. 5.
- [40] R. Abbasi, P. Martinez, R. Ahmad, The digitization of agricultural industry – a systematic literature review on agriculture 4.0, *Smart Agric. Technol.* 2 (2022) 100042.
- [41] C.M. Viana, D. Freire, P. Abrantes, J. Rocha, P. Pereira, Agricultural land systems importance for supporting food security and sustainable development goals: A systematic review, in: *Science of the Total Environment*, 2022, p. 806.
- [42] Kalaivanan, C., Tamilselvan, P., & Dhineshkumar, S. (2021). An intelligent autonomous spraying system for crop fields. In 2021 5th International Conference on Intelligent Sustainable Systems (pp. 862-867). IEEE. doi: 10.1109/ISS51518.2021.9391036
- [43] Kalaivanan, C., Tamilselvan, P., & Dhineshkumar, S. (2021). An intelligent autonomous spraying system for crop fields. In 2021 5th International Conference on Intelligent Sustainable Systems (pp. 862-867). IEEE. doi: 10.1109/ISS51518.2021.9391036
- [44] Chen, Y., Xu, L., Li, Y., & Zhang, X. (2022). Design of an autonomous agricultural spraying robot based on deep learning. In *International Conference on Computer Science, Intelligent System and Environment* (pp. 427-434). Springer. doi: 10.1007/978-981-16-0406-3\_42