

Perimeter Security Alert For Fisherman Using Arduino IDE

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Abstract- In day-to-day life we hear about many tamil fishermen being caught and put under Sri lanka custody and even killed. The sea border between the countries is not easily identifiable, which is the main reason for this crossing border cruelty. Here we have designed a system using embedded system which protects the fishermen by notifying the country border to them by using Global Positioning System (GPS) and Global system for mobile communication (GSM). We use GPS receiver to find the current location of the fishing boat or vessel. Using GPS, we can find the current latitude and longitude values and is sent to the microcontroller unit. Then the controller unit finds the current location by comparing the present latitude and longitudinal values with the predefined value. Then from the result of the comparison, this system aware the fishermen that they are about to reach the nautical border. The area is divided into four zones- normal zone, warning zone, zone near to restricted zone and finally the restricted zone. If the boat is in normal area, then the LCD displays normal zone. Thus they can make it clear that the boat is in normal area. In case it moves further and reaches the warning zone. The LCD displays warning zone. If the fisherman ignores the warning or fail to see the display and move further, and if the boat enters the zone nearer to the restricted zone the alarm will turn on and the speed of the boat engine automatically gets controlled by 50%. If the fisherman did not take any reaction about the alarm and move further, then the boat will enter into the restricted zone, the alarm continues to beep as before, and once it touches the restricted zone, the boat engine gets off by the control of fuel supply to engine.

I. INTRODUCTION

The Tamil Nadu fishermen even today invoke the historical rights and routinely stay into the International Maritime Boundary Line (IMBL) for fishing. From Tamil Nadu about 18,000 boats of different kinds conduct fishing along the India- Sri Lanka maritime border. But by accidentally crossing the border without knowledge, they get shot by the Lankan navy. This leads to loss in the both humans as well as their economic incomes. We have developed a system which eliminates such problems and saves the lives of the fishermen.

II. WORKING PRINCIPLE

The GPS Modem will continuously give the signal which determines the latitude and longitude and indicates the position of the fishermen to them. Then it gives the output which gets read and displayed in the LCD. The same data is sent to the mobile of the fisherman and simultaneously the same data is sent security. An EEPROM is used to store the data, received by GPS receiver. The hardware which interfaces with microcontroller are LCD display, GSM modem and GPS Receiver. GPS (Global Positioning System) is increasingly being used for a wide range of applications. It provides reliable positioning, navigation, and timing services to worldwide users on a continuous basis in all weather, day and night, anywhere on or near the Earth. 28 satellites inclined at 55° to the equator orbit the Earth every 11 hours and 58minutes at a height of 20,180 km on 6 different orbital Lanes and each one of these satellites has up to four atomic clocks on board. All we require is an accurate clock. By comparing the arrival time of the satellite signal with the onboard clock time, at which the signal was emitted, the latitude and longitudinal degree of the boat's location is determined. The current design is an embedded application, which will continuously monitor a moving Boat and once the boat goes beyond the level of the defined layer the particular operation will be done. For doing so an AT89c51microcontroller is interfaced serially to a GSM MODEM AND GPS receiver.



Fig1. GPS Working

III. EXISTING SYSTEM

At the present time there are few existing systems which help to identify the current position of the boats/ships using GPS System and view them on an electronic map. For the purpose of identification the fisherman are using the GPS72h, equipment used for the navigation in sea. It provides the fastest and most accurate method for mariners to navigate, measure speed, and determines location. This system enables increased levels of safety and efficiency. It ensures whether the ship reaches its destination safely. The accurate position information becomes even more critical as the vessel departs from or arrives in port.

IV. PROPOSED SYSTEM

The proposed system uses a GPS receiver which receives signal from the satellite and gives the current position of the boat. The proposed system is used to detect the border of the country through the specified longitude and latitude of the position, not only between Sri Lanka and India but all over the world. The particular layer level i.e. border can be predefined and this can be stored in microcontroller memory. The current value is compared with predefined values and if these values are same, immediately the particular operation will be done i.e, the microcontroller gives instruction to the alarm to buzzer. It also uses a message transmitter to send message to the base station which monitors the boats in the sea. The system provides an indication to both fisherman and to coastal guard. Thus it saves the lives of the fisherman and alerts the base station to provide help.

V. ARCHITECTURE

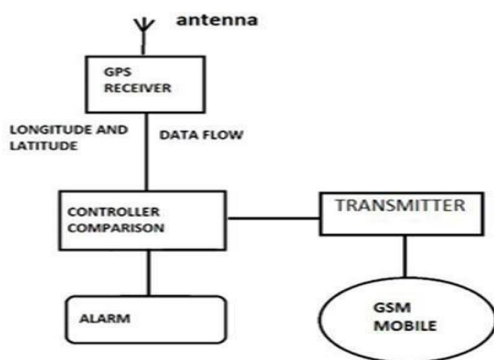


Fig2. Block diagram

VI. SYSTEM FLOW DIAGRAM

The GPS receiver receives the signal and converts it into desired data message. The data is sent to

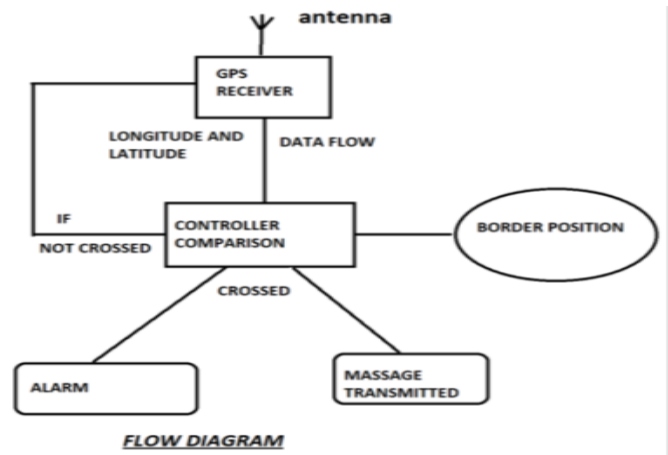


Fig.3 System Flow Diagram

microcontroller and microcontroller extracts the latitude and longitude from the data. The positions are compared with the stored Boundary latitude and longitude positions. If the vessel is found beyond the border, then an alarm is generated along with a message transmission by a GSM.

VII. GLOBAL POSITIONING DEVICE

A GPS navigation device is any device that receives Global Positioning System (GPS) signals for the purpose of determining the device's current location on Earth. GPS devices provide latitude and longitude information, and some may also calculate altitude. GPS devices are used in military, aviation, marine and consumer product applications.

VIII. GPS ACCURACY

The accuracy of GPS depends on the type of receiver. Most hand-held GPS units have about 10-20meter accuracy. Other types of receivers use a method called Differential GPS (DGPS) to obtain much higher accuracy. DGPS requires an additional receiver fixed at a known location nearby. Observations made by the stationary receiver are used to correct positions recorded by the moving units, producing an accuracy greater than 1meter

IX. CONTROLLER

Microcontroller receives the data from the GPS receiver through UART. The data received contains many details along with latitude and longitude. The latitude and Longitude of the current position is separated from the detailed data from GPS. The current positions are compared with already stored latitude and longitude of countries boundary locations.

At first the latitude is compared with stored latitude which identifies if the current position is located near to the boundary. If the latitude matches then the adjacent latitudes and longitudes of the present latitude is retrieved from the microcontroller. The current position received from GPS is stored as S1(latitude), S2 (longitude). The latitude S1 is compared with stored latitudes.

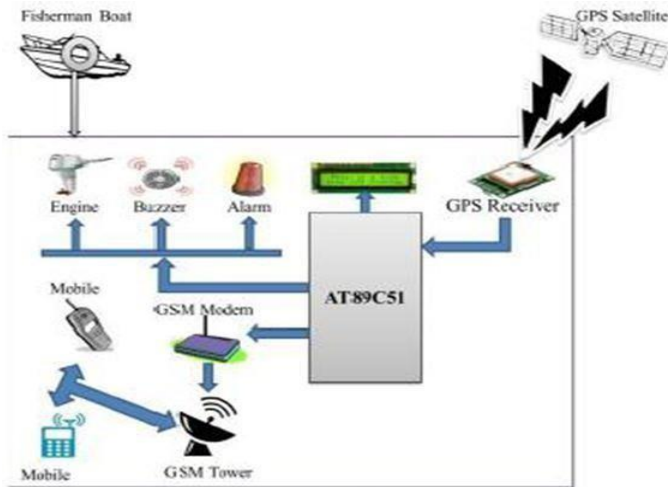


Fig.4 Controller

X. DISPLAY UNIT

A LCD display16x2 is used for displaying the latitude and longitude. LCD display is connected to port 1 of the Microcontroller. Every pin of port 1 is connected to LCD display. Message is sent through commands via serial communication.

XII. GSMMODULE

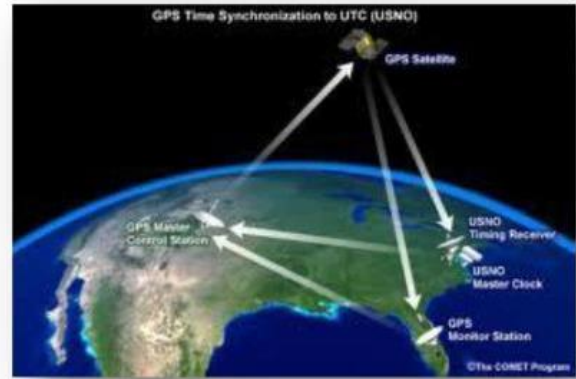
GSM module is used for transmission of message seeking assistance. GSM cannot be used in oceans as towers cannot be placed in oceans. Thus, CDMA network or satellites can be used for message transmissions. When vessel crosses border, the stored message along with current latitude and longitude positions is sent to the desired GSM module which is stored already.

XIII. CALCULATING THE POSITIONS

Because GPS receivers do not have atomic clocks, there is a great deal of uncertainty when measuring the size of the Spheres. Each radius corresponds to the distance calculated to the satellite. All possible distances to the satellite are located on the circumference of the circle. If the position above the satellites is excluded, the location of the receiver is at the exact point. Where the three circles intersect beneath the satellites. Although the distance to

the satellites can only be roughly estimated at first, a GPS receiver can precisely calculate these distances relative to each other. Because the relative size of the spheres is known, there is only one possible point where they can intersect.

If latitude match, then adjacent latitude and longitudes (X1, Y1 and X2, Y2) are retrieved from stored table and substituted in the equation given below:



Position	Latitude	Longitude
Position1	12°05'.0N	82°03'.0E
Position2	12°05'.8N	82°05'.0E
Position3	12°08'.4N	82°09'.5E
Position4	12°33'.0N	82°46'.0E

Fig.5 Calculating the Position

$$\checkmark (Y - Y1)/(Y2 - Y1) = (X - X1)/(X2 - X1)$$

By simplification, we get ax + by = c Now, S1 and S2 are substituted in above equation of line Here two cases are possible:

Case 1: If LHS<RHS, then vessel is inside the country border. When vessel is inside country’s border, the microcontroller gets the input from GPS receiver after a short delay loop-Latitude and longitude is extracted and manipulation with the new locations is done in the algorithm.

Case 2: If LHS>RHS, then vessel has crossed border.

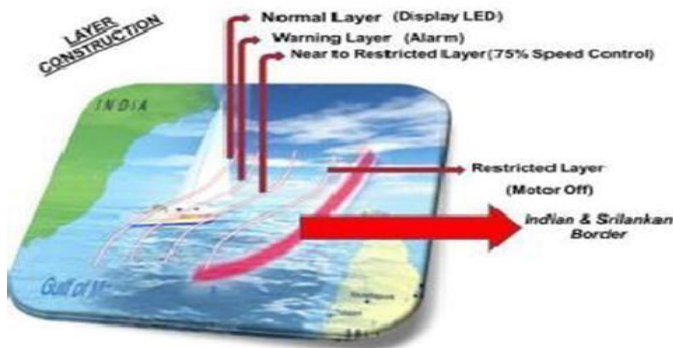


Fig.6 Layer

When vessel crosses border, an alarm is generated immediately. Along with alarm a signal is also sent to GSM module for transmission of message to desired sender. Alarm continues until the vessel comes back inside the country's border.

XIV. MARI TIME BOUNDARY BETWEEN INDIA ANDSRILANKA

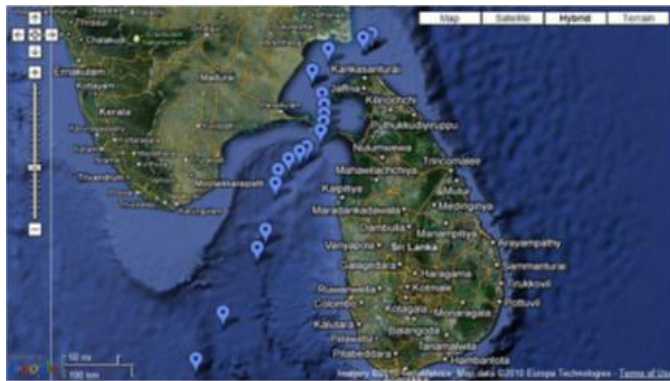


Fig.6 Boundary Between India and Srilanka

The boundary between India and Sri Lanka in the waters from Adam's Bridge to Palk Strait shall be arcs of Great Circles between the following positions, in the sequence given above, defined by latitude and longitude.

The boundary points are marked above. These points should be stored in microcontroller. The computation is done in microcontroller with these points. Thus the vessel crossing the border is being calculated.

XV. CONSEQUENCE

- Boat Position and Navigation System contains,
- Layer1: Green LED indication
- Layer2: Red LED indication
- Layer3: Alarm indication & speed control
- Layer 4: Engine off

XVI. FUTURE SCOPE

We can use the EEPROM to store the previous Navigating Positions up to 256 locations. we can navigate up to Number of locations by increasing the memory of EEPROM. We can reduce the size of the kit by using GPS+GSM on the same module of GPS navigator. We can increase the accuracy up to 3m by increasing the cost of the GPS receivers.

XVII. BENEFITS

The hijack of the ship by the pirates can be eradicated. The lost ship wrecks due to natural calamities can be identified By keeping the kits in the entire boats and by knowing the locations of all the boats we can use our kit to assist the traffic. In-case of any accident on the sea. it can be detected by the system and the accident location of the boat is sent to the rescue team.

XVIII. APPLICATION



Fig.7 Application

We can use this device also as bomb detector. Location of any lost vehicle could be found by this device.

XIX. VERIFICATION AND RESULTS

The hardware components and software are connected properly. After giving the power supply, the ultrasonic sensor detects the level of garbage and separates the waste from the bin using image processing and the output is given.

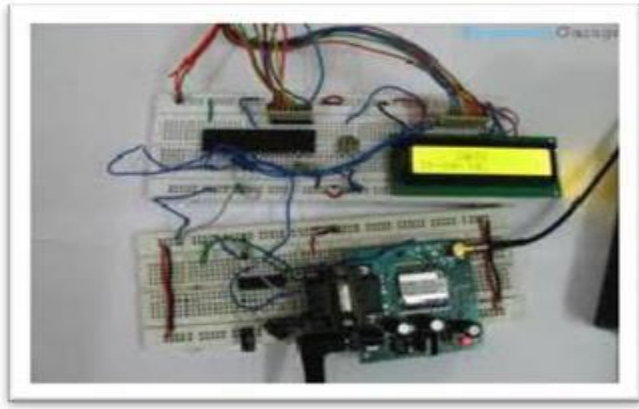


Fig.9 Result

XX. CONCLUSION

Thus the fishermen can easily identify the national sea borders and therefore prevents them from entering their area. Thus, saving their lives and providing good relationship with the other countries. Also, the piracy of ship can be easily brought under control.

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