# Dynamic Analysis Study of Off-Shore Platform Subjected To Wave Loading

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Abstract- Off shore structures design are very different from conventional structures. Hence there is need to perform structural analysis of off-shore platforms for static as well as dynamic loading. This paper details the results obtained from static and dynamic analysis, considering both operational and ultimate limit state performance characteristics, designed at high basin. The existing platforms at high region are affected by continuous sea state and operational state loading. So, it becomes a necessity that the structures are design for the purposes should be a reliable one. The Static load and dynamic load analysis done in this study, using the SAP2000 v14 software helps to analyze and predict the performance of structure at, when Subjected to various load cases which will help in future to design it properly and accurately. In this paper various loads such as wave load, wind load both for airy and stokes law and earthquake load have been used to calculate the displacement and bending moment for design.

# I. INTRODUCTION

## 1 General

## 1.1 General

Fixed offshore platforms are unique structures since they extend to the ocean floor and their main function is to hold industrial equipment that services oil and gas production and drilling. Robust design of fixed offshore structures depends on accurate specification of the applied load and the strength of the construction materials used. Most loads that laterally affect the platform, such as wind and waves, are variable, so the location of the platform determines the met ocean data. In general, the loads that act on the platform are:

- Wind loads
- Wave loads
- Current loads
- Earthquake loads
- Installation loads
- Other loads such as impact load from boats

## 2. Loading on Offshore Structures According To ISO:

 Gravity loads consist of the dead load and the live (imposed) load.

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Dead Load

The dead load is the platform's own overall weight and, in addition, the weight of the equipment, such as piping, pumps, compressors, separators, and other mechanical equipment, used during operation of the platform. The overall weight of platform structure upper decks (topside) includes the piling, superstructure, jacket, stiffeners, piping and conductors, corrosion anodes, decking, railing, grout, and other appurtenances. Sealed tubular members are considered either buoyant or flooded; whichever produces the maximum stress in the structure analysis.

		Weight (Tons)	Percentage of Tota
Τ	Heck	1 11 11 11	
	Drilling deck		
	Plate	72.	11
	Production deck		
	Pale	52	7.8
	Grating	1.0	0.16
	Subtotal	125	18.8
2.	Deck beams		
	Orilling deck	174	26.3
	Production deck	56	8.5
	Setteetal	230	34.8
3.	Tubular trusses	146	22,1
4	Legs	:105	15.9
5	Appurtenances		
	Vent stack	6	0.9
	Stairs	12	1.8
	Handrails	4	0.6
	Lifting eyes	2	0.3
	Drains	6	0.9
	Fire wall	4	1.7
	Stiffeners	14	2,2
	-	661	100

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ш	Component Description	Weight, Ton	% of Total Weight	Sub-system % of Total Weight
1-	1 eggs			_
	Joint can	177	14.6	
	In between tubular and others	309	25.4	40
2.	Uraces			
	Diagonal in vertical plan	232	19.1	
	Horizontal	163	13.4	
	Diagonal in horizontal plan-	100	8.2	40.7
3.	Other framing:			
	Conductor framing	35	2.9	
	Launch trusses and runners	82	6.7	
	Miscellaneous framing	2	0.2	9.8
4.	Appurtenances			
	Boat landing	20	2.3	
	Barge bumpers	29	2.4	
	Corrosion anodes	20	1.8	
	Walkways	16	1.3	
	Mud mats	5	0.4	
	Lifting eyes	2	0.2	
	Clasure plates	2	0.2	
	Hooding system	7	0.6	
	Miscellaneous	4	0.3	9.5
				100%

Virtually all the decisions about the design of a platform depend on the number of jacket legs. Soil conditions and foundation requirements often control the leg size. The function of the jacket is to surround the piles and to hold the pile extensions in position all the way from the mud line to the deck sub-structure. Moreover, the jacket legs provide support for boat landings, mooring. Offshore Structure Loads and Strength bits, barge bumpers, corrosion protection systems and many other platform components. The golden rule in design is to minimize the projected area of the structure member near the water surface in high wave zones in order to minimize the load on the structure and to reduce the foundation requirements.

## Live Load

- Live load is the load imposed on the platform during its use; live loads change from one mode of operation to another. They include:
- The weight of drilling and production equipment.
- The weight of living quarters, heliport and other life-support equipment.
- The weight of liquid in storage tanks.
- The forces due to deck crane usage.

The live load depends on the owner's requirements, and normally it is included in the statement of requirements (SOR) or basis of design (BOD) documents. See Table 2.3 for guidelines on live loads. For general deck area loading, the topside deck structure should be designed for the specified imposed loads (outlined in Table 2.4) applied to open areas of the deck, where the equipment load intensity is less than the values shown. DNV (2008) states that the variable functional loads on deck areas of the topside structure should be based on the values in Table 2.5. These values are considered

guidelines, so they should be defined in the design criteria, which will be approved by the owner. If the owner needs to increase the load more than is noted in the code, it should be stated in the BOD and the detailed drawings should include the load on the deck. In Table 2.5, the loads that are identified for the local design are used for the design of the plates, stiffeners,

	Uniform Load on Beams and Decking, kN/m <sup>2</sup> (lbs/ft <sup>2</sup> )	Concentrated Live Load on Decking, kN/m <sup>2</sup> (lbs/ft)	Concentrated Load on Beams kN (kips)
Walkways and stairs	4.79 (100)	4.378 (300)	4.44 (1)
Areas over 400 ft <sup>2</sup>	3.11 (65)		
Areas of unspecified light use	11.97 (250)	10.95 (750)	267 (60)
Areas where specified loads are supported directly by beams		7.3 (500)	,

		Loadin	ig, kN/m <sup>2</sup>		
	-	Membe	r Category		_
Area	Deck Plate, Grating and Stringers	Deck Beams	Main Framing	Jacket and Foundation	Point Load, kN
Laydown areas	12	10	a		30
Open deck areas and access hatches	12	10	a	C	15
Mechanical handling routes	10	5	А	<b>C</b>	30
Stairs and landing	2.5	2.5	ь	-	1.5
Walkways and access platforms	5	2.5	ā	с	5 d

- For the design of the main framing, two cases should be considered
- with 25 NV/m<sup>2</sup> on the laydown accordance; including attack received and including the second second received and the laydown area, and a condition all equipment leads but no future equipment, together with 2.5 kN/m<sup>2</sup> of the laydown area, and a total authorial five fead of 50 tims. This five food should be applied at the laydown area, and a total authorial five fead of 50 tims. This five food should be applied at
- a constant uniformly distributed load over the open areas of the deck.

  "Loading for deck plate, grating and stringers should be combined with structural dead loads an
- designed for the most onerous of the following:

  I coding over entire contributory deck area.
- A point load (applied over a 300 mm × 300 mm footprint)
   Functional loads plus design load on clear areas.
- For substructure design, deck loading on clear areas in extreme storm conditions may be reduced to zero in new or die faul that the alleform is not normally manned during storm conditions. A rotal fee load 700 kN at the topsicic center of gravity should be assumed for the design of the jacket and foundations. Profits load for access platform beam design is to be 10 kN and 5 kN for deck grating and stringer; topscticity.

beams and brackets. The loads for the primary design should be used in the design of girders and columns. The loads for the global design should be used for the design of the deck main structure and substructure. From Table 2.5, the wheel loads should be added to distributed loads where relevant. (Wheel loads can be considered as acting on an area of  $300 \times 300$  mm.) Point loads, which should be applied on an area  $100 \times 100$  mm, and at the most severe position, should not be added to wheel loads or distributed loads. The value of q in Table 2.5 is to be evaluated for each case. Laydown areas should not be designed for less than 15 kN/m2. The value of f in Table 2.5 is obtained from:

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	Load D	esign	Primary Design	Global Design
	Distributed Load, kN/m <sup>2</sup>	Point Load, kN	Apply Factor for Distributed Load	Apply Factor to Primary Design Load
Storage areas	q	1.5q	1.0	1.0
Laydown areas	q	1.59	f	í
Lifeboat platforms	9.0	9.0	1.0	May be ignored
Area between equipment	5.0	5.0	ť	May be ignored
Walkways, staircases and platform crew spaces	4.0	4.0	I	May be ignored
Walkways and staircases for inspection only	3.0	3.0	f	May be ignored
Areas not exposed to other functional loads	2.5	2.5	1.0	May be ignored

Global loads should be established based on the worst-case-scenario characteristic load combinations complying with the limited global criteria for the structure. For buoyant structures, these criteria are established by requirements for the floating position in still water and intact and damage stability requirements, as documented in the operational manual, are considered for variable loads on the deck and in tanks. In calculating the dry weight of piping, valves and other structure supports, there should be a 20% increase as a contingency for all estimates of piping weight, because in most cases there are changes in piping dimensions and location during the lifetime of the structure. In addition, all the piping and fittings are calculated in the operating condition, assuming they are full of water with specific gravity equal to 1, with a 20% contingency.

When calculating the dry weight of all equipment, equipment skid, storage and helicopter, a contingency allowance of 10% should be included. From a practical point of view, Table 2.6 presents the minimum uniform live load values from industrial practices.

Platform Deck	Uniform Load, kN/m <sup>2</sup> (lb/ft <sup>2</sup>
Helideck	
Without helicopter	14 (350)
With Bell 212	2 (40)
Mezzanine deck	12 (250)
Production deck	17 (350)
Access platforms	12 (250)
Stairs/wal kways	4.7 (100)
Open area used in conjunction with the equipment operating and piping loads for operating and storm conditions	2.4 (50)

	Load	Direction
Structural Item	Vertical	Horizontal
Rated load of cranes	100%	100%
Support of light machinery	20%	0%
Support of reciprocating machinery	50%	50%
Boat landings	200 kips (890 kN)	200 kips (890 kN)

## Impact Load

For structural components carrying live loads that could face impact, the live load must be increased to account for the impact effect, as shown in Table 2.7.

# • Design for Serviceability Limit State

The serviceability of the topside structures can be affected by excessive relative displacement or vibration in vertical or horizontal directions. Limits for either can be dictated by the following:

- Discomfort to personnel.
- Integrity and operability of equipment or connected pipework.
- Limits to control deflection of supported structures, such as flare structures.
- Damage to architectural finishes.
- Operational requirements for drainage (free surface or piped fluids).

Unless stricter limits are established by the platform owner's company or regulator, the limits of deflection (presented in "Deflections" below) should apply.

## Vibrations

All sources of vibration should be considered in the design of the structure. At a minimum, the following should be reviewed for their effect on the structure:

- Operating mechanical equipment, including that used in drilling operations.
- Vibrations from variations of fluid flow in piping systems, in particular slugging.
- Oscillations from vortex shedding on slender tubular structures.
- Global motions from the effect of environmental actions on the total platform structure.
- Vibrations due to earthquake and accidental events.

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Design limits for vibration should be established from operational limits set by equipment suppliers and from the requirements for personnel comfort, health and safety. It is important to note that large cantilevers, whether they are simple beams or trusses forming an integral part of the topside platforms, but excluding masts or booms, normally should be proportioned to have a natural period of less than 1 second in the operating condition.

#### Deflections

The final deflected shape, max, of any element or structure has three components:

$$max = 1 + 2 - 0$$
 (2.2)

where 0 is any precamber of a beam or element in the unloaded state if it exists, 1 is the deflection from the permanent loads (actions) immediately after loading and 2 is the deflection from the variable loading and any timedependent defor-mations from permanent loads.

The maximum values for vertical deflections, based on ISO 9001, are given in Table 2.8. The limiting values for vertical deflection based on a load and resistance factor design (LRFD) are given in Table 2.9. Lower limits may be necessary to limit ponding of surface fluids and to ensure that drainage systems function correctly. Horizontal deflections generally should be limited to 0.3% of the height between floors. For multifloor structures, the total horizontal deflection should

## Gravity Loads

Structural Element	$\Delta_{\mathrm{max}}$	$\Lambda_2$
Floor beams	1/200	1/350
Cantilever beams	<i>U</i> 100	L/150
Deck plate		2t or b/150

Structure Member	$\Delta_{\text{max}}$	$\Delta_2$
Deck beams	L/200	L/300
Deck beams supporting plaster or other or ttle finish or nonflexible partitions	L/250	L/350

not exceed 0.2% of the total height of the topside structure. Limits can be defined to limit pipe stresses and to avoid riser or conductor overstress or failure. Some designers allow higher deflections for structural elements where serviceability is not compromised by deflection.

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## II. LITERATURE REVIEW

# 1. Buckling Analysis of Underwater Cylindrical Shells Subjected To External Pressure

International Journal of Innovative Research in Advanced Engineering (IJIRAE) ISSN: 2349-2163Volume 1 Issue 10 (November 2014)

## Rinu Cherian Iin

In the field of structural mechanics the word shell refers to a spatial, curved structural member. In shells, the external loads are carried by both membrane and bending response. The effect of such responses needs careful observation. This project fulfills the need on study of behavior of shell structures by both mathematical and numerical methods. In the present development, the Donnell's relation forms the basis of stability equation for circular cylindrical shells. The effect of stiffeners on cylindrical structures has been studied, by varying the geometry and orientation of stiffeners. The paper aims to analyze the cylindrical section of an underwater pressure hull, using finite element analysis and strengthen it accordingly. The project considers the finite element method for static structural and deflection analysis of underwater cylindrical structure by using ANSYS 15software

# 2. Dynamic Behavior of Jacket Type Offshore Structure Jordan Journal of Civil Engineering, Volume 6, No. 4, Anis A. Mohamad Ali, Ahmed Al-Kadhimi and Majed Shaker

Unlike structures in the air, the vibration analysis of a submerged or floating structure such as offshore structures is possible only when the fluid-structures is understood, as the whole or part of the structure is in contact with water. Using the commercial F.E.A. program ANSYS (v.12.0) (to model the Winkler and Brick-full bond models) and program ABAQUS(v.6.9) (to model the Brickinterfacemodel), the stress matrix considering a dynamic load was superposed on the stiffness matrix of the structure. A time domain solution is recommended, using the generalized Morison's equation by FORTRAN90 program to construct a program to calculate the wave forces, and Airy's linear and Second Order Stoke's wave theories are employed to describe the flow characteristics by usingMAPLE13 program (to solve and apply the boundary conditions of the problems on Laplace's equation), and the results are compared and discussed. Both free and forced vibration analyses are carried out for two case studies

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# 3. Nonlinear Analysis of Offshore Structures under Wave Loadings

WCEE

## Shehata E. Abdel Raheem

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The structural design requirements of an offshore platform subjected wave induced forces and moments in the jacket can play a major role in the design of the offshore structures. For an economic and reliable design; good estimation of wave loadings are essential. A nonlinear response analysis of a fixed offshore platform under wave loading is presented, the structure is discretized using the finite element method, wave force is determined according to linearized Morison equation. Hydrodynamic loading on horizontal and vertical tubular member sand the dynamic response of fixed offshore structure together with the distribution of displacement, axial force and bending moment along the leg are investigated for regular and extreme conditions, where the structure should keep production capability in conditions of the one year return period wave and must be able to survive the 100 year return period storm conditions. The result of the study shows that the nonlinear response investigation is quite crucial for safe design and operation of offshore platform.

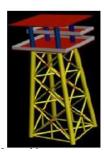
# III. PROBLEM STATEMENT

The following studied platform is a fixed Jacket-Type platform currently installed in the Suez gulf, Red sea,1988 shown in Figure 3, The offshore structure is a four legs jacket platform, consists of a steel tubular-space frame. There are diagonal brace members in both vertical and horizontal planes in the units to enhance the structural stiffness. The Platform was originally designed as a 4-pile plat form installed in 110 feet (110' =33.5 m) water depth.

The Top side structure consists of Helipad 50'x50' at Elevation, EL. (+54') & Production deck 50'x50' at EL. (+26'); Top of jacket at EL (+12.5'). The Jacket consists of 4 legs with 33 inch Outer Diameter (33" O.D.) & 1 inch Wall Thickness (1"W.T.) Between EL. (+10') and EL. (-23') and (33" O.D. x 0.5" W.T.) between EL. (-23') and EL. (-110'). In the splash zone area that is assumed to extend from EL. (-6') to EL. (+6') LAT. (Lowest Astronomical Tide).

 $\cdot$  The jacket legs are horizontally braced with tubular members (8.625" O.D. x 0.322" W.T.) at elevations (+10'); (10.75" O.D. x 0.365" W.T.) at elevations (-23'); (12.75" O.D. x 0.375" W.T.) at



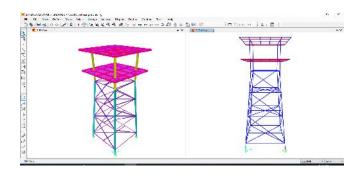


# IV. FEA MODELING IN ANSYS

Three comparative model of offshore jacket platform for 40m height considering self weight and hydrostatic pressure is modeled in ansys using SOLID 186 element.

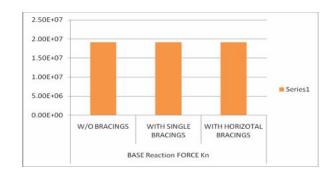
Model1: Without horizontal and diagonal bracings

Model2: With diagonal bracings Model3: With horizontal bracings



# V. RESULT AND DISCUSSION

## 1. Results for Base Reaction



# 2. Results fot Total Deformation

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 offshore platform with double bracing and knee bracing with 40 degree model, shows natural time period of 1.29 sec and 1.38 sec respectively, which is nearly close spaced value, while single bracing shows natural time period of 1.58 sec for same model, hence double and knee bracing perform quite well as compare to single bracing for natural time period.

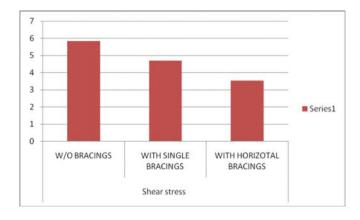
## 3. Result for Shear Stress

W/O BRACINGS

3

2

1 0



WITH SINGLE

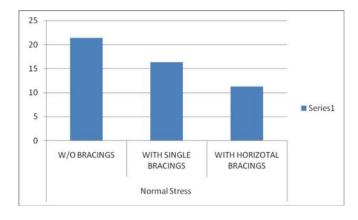
BRACINGS

Total Deformation mm

WITH HORIZOTAL

BRACINGS

# 4. Result For Normal Stress



# VI. CONCLUSION

- offshore platform with double bracing and knee bracing with 90 degree model, shows natural time period of 1.51 sec and 1.61 sec respectively, which is nearly close spaced value, while single bracing shows natural time period of 2.14 sec for same model, hence double and knee bracing perform quite well as compare to single bracing for natural time period.
- in study of offshore platform with double bracing and knee bracing with 60 degree model shows natural time

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