

Production of Non-Convnetional Energy Through Elevator

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Abstract- Aim: This paper presents Power Generation for permanent magnet Elevator motor To generation of the electricity by using conventional and non-conventional sources. The elevator motor is rated at KW in lifts. It Projection out, organizes, and assemblage complex and scattered information on multiple manner of elevator design, and presents them in an accessible and non-technical discourse. This paper is shows the way of controlling the load demand of power according to the availability of supply by using microcontroller atmega328

Keywords- atmega328, Estimation, Inputs, energy saving; efficiency; speed; long distances; comfort; safety

I. INTRODUCTION

In now days, the increasing demand of electricity is the main problem. Due to hug use of electricity it creates large demands related problems. The total electricity generating capacity of India from January 1, 2017 is 288,005 MW with 60.8% share from coal, 8.5% from gas, 3% from diesel 2% from nuclear and remaining 28% from Renewable Energy (RE) sources. In this study can be applied for future use of in existing system of elevator. In this paper, to overcome the loadshedding problem described a way to generate the electricity from conventional and non-conventional sources such like footstep, any type of rotary motion. The main advantage behind this system is that, it can generate the power according to the demand of load with less coast rather than the conventional electricity generating method.so, it can be design for the privet application as per demand of plant, industry and other uses

a) Objective :- The main objective behind this project is to generate the power using elevator motor for the various type of application.

II. MODEL DESCRIPTION

Block Diagram Specification :-

2.1] Microcontroller ATmega328

The ATmega328P is a low-power CMOS 8-bit microcontroller based on the AVR Enhanced RISC architecture. By executing powerful instructions in a single clock cycle, the ATmega328P achieves throughputs approaching 1 MIPS per MHz allowing the System designer to optimize power consumption versus processing speed.

2.2] Transformer:-

Step down transformer is the first part of regulated power supply. To step down the mains 230V A.C. we require step down transformer. Following are the main characteristic of electronic transformer.

1. Power transformers are usually designed to operate from source of low impedance at a single freq.
2. It is required to construct with adequate insulation of obligatory dielectric strength.

Transformer ratings are expressed in volt-amp. The volt-amp of each secondary winding or windings are added for the total secondary VA. To this are added the load losses **Voltage:**most irons run from the mains at 240V. However, low voltage types (e.g. 12V or 24V) generally form part of a "soldering station" and are designed to be used with a special controller made by the same manufacturer

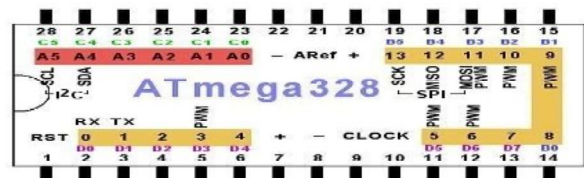


Figure 1:- Pin structure of ATmega328

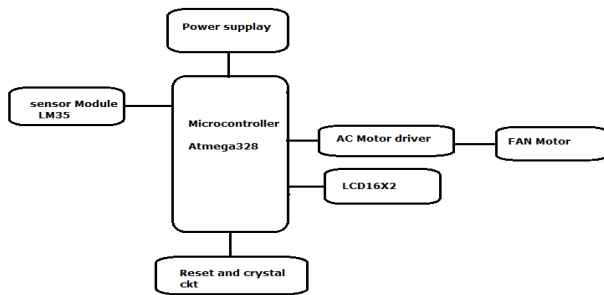


Figure 2:- Block Diagram of module.

2.3) Voltage Regulators:-

Here the voltage regulators are used to generate the dc regulated voltage supply. One 7805 three terminal voltage regulator has input, ground and output pins. Specifications: Available o/p D.C. Voltage = + 5V. Line Regulation = 0.03, Load Regulation = 0.5 V_{in} maximum = 35 V Ripple Rejection = 66-80 (db)

2.4) Crystal Oscillator:-

A crystal oscillator is an electronics oscillator circuit that uses the mechanical resonance component of vibrating crystal of piezoelectric material to create an electrical signal with a precise 16MHz frequency.

2.5) 16*2 LCD:-

It is an electronic display kit which is used for a wide range of applications. The 16*2 LCD means it can have 16*2 line structure i.e. 16 characters per line. In this LCD each character is displayed in 5*7 pixel matrix. This display is economical, easily programmable and has no limitation of displaying special & custom characters.

2.6) Arduino:

Arduino is an open-source electronics prototyping platform based on flexible, easy-to-use hardware and software. It is intended for artists, designers, hobbyists, and anyone interested in creating interactive objects or environments. Arduino can sense the environment by receiving input from a variety of sensors and can affect its surroundings by controlling lights, motors, and other actuators. The microcontroller on the board is programmed using the Arduino programming language and the Arduino Development Environment. Arduino projects can be stand-alone, or they can communicate with software running on a computer.

2.6) Rectifier Unit

Rectifier unit is a device which converts A.C. into pulsating D.C. Generally a semi-conducting diode is used as a rectifying element due to its property of conducting current in one direction only. Generally there are two types of rectifier.

- 1) Half wave rectifier
- 2) Full wave rectifier.

In a half wave rectifier only half cycle of mains A.C. is rectified so its efficiency is very poor. So we use a full wave bridge type rectifier, in which four diodes are used. In each half cycle, two diodes conduct at a time and we get maximum efficiency at o/p.

2.7) Filter Circuit

Generally a rectifier is required to produce pure D.C. supply for use at various places in the electronic circuit. However, the o/p of a rectifier has a pulsating character i.e. if such a D.C. is applied to an electronic circuit it will produce a hum i.e. it will contain A.C. and D.C. components. The A.C. components are undesirable and must be kept away from the load. To do so a filter circuit is used which removes (or filters out) the A.C. components reaching the load. Obviously a filter circuit is installed between the rectifier and the voltage regulator.

III. WORKING

This is an expensive fully transistorized inverter capable of driving medium loads of the order of 40 to 60 watts using a battery of 12V, 7.8Ah or higher capacity. Transistors T1 and T2 (BC548) form a 50 Hz multivibrator. For obtaining correct frequency, the values of resistors R3 and R4 may have to be changed after testing. The complementary outputs from the collectors of transistors T1 and T2 are given to PNP Darlington pair driver stages formed by transistors T3-T4 and T6-T7 (utilizing transistors BD140 and 2N6107). The outputs from the drivers are fed to transistors T5 and T8 (2N3055) connected for push pull operation. Somewhat higher wattage can be achieved by increasing the drive to 2N3055 transistors (by lowering the value of resistors R7 and R8 while increasing their wattage). Suitable heat sinks may be used for the output stage transistors. Transformer X1 is a 230V to 9V-0-9V, 2A secondary used in reverse.

IV. POWER SUPPLY DESIGNING

Power Supply Designed and Circuit Connection

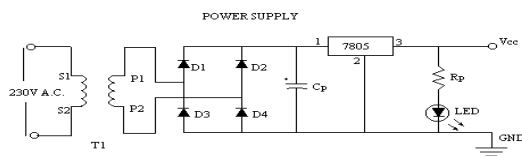


Figure 2: - Block Diagram of Power Supply

V. RESULT

In this paper we observed that, it is one of the best convenient method to avoid the load demand problems as well as provide the free power when the lifts is in working condition. In future this system can be also implemented as regenerative lift unit.

VI. CONCLUSION

Here from above we conclude that generation of electrical energy with elevator is cheaper than coasty conventional method for the specific requirement. It is one of the alternative method in presence of failure of power supply during emergency.

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