

# Modeling and Analysis of Maximum Power Point Tracking for Photovoltaic System using Fuzzy Logic Controller

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**Abstract-** This paper presents the simulation and analysis of maximum power point tracking (MPPT) for photovoltaic (PV) system using Fuzzy Logic Controller (FLC) algorithm. The ultimate aim of the paper is, a new one input FLC to improve the maximum power point tracking capability for PV system under partial shading condition. The fuzzy control method is used for haul out the highest power source from the PV scheme with change in value of temperature and under variable value of solar irradiations. The scheme rigging the FLC as a MPPT controller is to take out the highest voltage and power source profile from PV scheme under variable temperature and solar irradiations. The dc-dc converter is used to boost the tracked voltage from the PV system. The membership function of FLC for PV voltage and current sampled with variations of solar irradiations and temperature change. Fuzzy logic controller stand MPPT can pull out the highest power from PV system compare to other conventional MPPT algorithms. Therefore overall proposed system output voltage can be enhanced. The effectiveness of the proposed system is proved with the help of simulation. The simulation is performed in MATLAB/Simulink.

**Keywords:** Photovoltaic (PV) Systems, DC-DC Converters, Maximum Power Point Tracking (MPPT), Fuzzy Logic Controller (FLC)

## I. INTRODUCTION

In recent years, the growths of energy demand and of the pollution from use of fossil fuels are pushing the public to use renewable energies. In this context, solar energy is one of the major renewable energy sources that appears as a solution to our problems of energy production. Moreover, this energy resource seems to be the most promising, and inexhaustible. However, the generation of this kind of energy is non-linear. It varies and depends on insolation and ambient temperature. Therefore, the operating point of photovoltaic doesn't always coincide with the point of maximum power. For this, we used a mechanism research called maximum power point tracker (MPPT) to extract the maximum power [1-5].

Due to power require and ecological accountability, growing energy values, global warming and air pollution, the photovoltaic (PV) systems are becoming more effective and alternative sources of energy. Currently the solar scheme has turn into one of the majority gifted renewable source due to its infinite with other environmental rewards. In daily activities the energy plays a significant function, as there is much increase in population and industrial applications. It is one of renewable energy source, which has more potential of counteracting a significant amount of the world's energy requirement [6-14]. The main fuels like coal, diesel, and petrol, nuclear and other natural gases are depleting day by day. PV array has concerned additional concentration in the very last few years as it meets the requirements of creature environmentally well-suited with reserve preserving. The occurrence of increasing the rate of energy expenditure and supply is decreasing that the result into energy deficiency [15-25].

The PV system is set to play a continually increasing part in generating the form, the affecting the exterior and creation of construction. When linking the PV array to the load, the photovoltaic voltage and current value PV a cell varies according to the solar irradiations. The source produced from the PV scheme is not sufficient to run the motor load system, for that the DC-DC boost up converter employed to get superior the engendered PV power [26-36]. Generally used MPPT algorithms like perturb and observe (P&O), incremental conductance method, neural network technique, short circuit process and fuzzy logic control to get better output from the PV cells. In this proposed system, the simulation of highest power point path with fuzzy logic controller technique fed voltage source inverter was realized. The PV system investigated with change in temperature and solar radiations and for extracting the maximum power fuzzy logic control MPPT prepared [37-48].

In the literature, the fuzzy logic control method has shown its advantage in terms of performance, robustness and flexibility. This method could quickly respond to the variation of environmental conditions, by keeping PV system working at maximum power point at all times, and eliminate the

oscillation power around point of maximum power [49-60]. There are always two inputs in a MPPT fuzzy logic controller. This causes complexity in fuzzification, fuzzy rules and defuzzification. In this paper, a new one input MPPT fuzzy logic controller, by using only one input  $dP/dV$ , the structure of the proposed MPPT controller is simple. To show the control performance, numerical simulations were performed under the variation of environmental condition and load [61-68].

**II.PV ARRAY MODELLING**

The power circuit of PV array consists of current source, 2 diodes and resistors and load, which is shown in Fig 1.

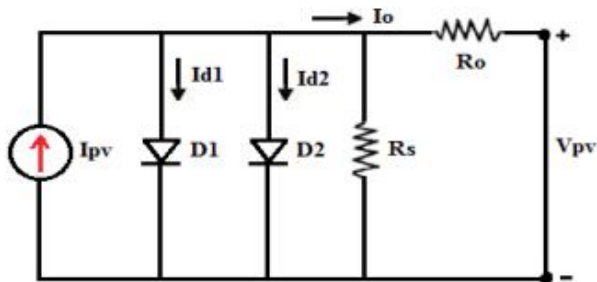


Fig. 1 Power circuit for PV array modelling

The photovoltaic or photo-electric unit is a power semiconductor apparatus to exchanges light to electrical source with PV consequence. When power of photon is more than the band gap of electron is released with surge of electron which generates the current flow in the circuit. Regularly, the solar cell model can be sculpted by a current source with an inverter system diode associated in equivalent to it. And it has both parallel and series type of resistance and where  $I_q$  – reverse use saturation current value of the device,  $p$ - electron charge in the device,  $V_n$  – the voltage across the device,  $r$  - Boltz fixed value and  $T$  is the branch temperature for the PV model. PV system assembled to generate the DC voltage from the light energy and a PV panel is one or more PV cell assembled, designed to provide a field connected unit, while a PV array is the smallest installed assembly of PV panels or modules, carry structures, practicalities and other components used for installation.

**III. MPPT METHOD**

A typical solar radiation converted into electrical energy by 35 to 45 percent from the solar panel. To progress effectiveness of the solar scheme highest power source point tracking is prepared. The extracting of maximum power decided when the solar irradiations and temperature will be constant. When the variations occur in solar irradiation and

temperature, the improved MPPT method has to implement. The dc-dc boost up converter supplementary in the PV array side in direct to augment the tracked source as of the PV scheme. Moreover with altering duty value of dc boost converter the requisite demand voltage could achieve, to facilitate gives the source voltage matched with the load voltage. Based on this situation PV voltage source with current value deliberated and The PV array scheme, a P-V characteristic of is exposed with Fig 2.

The P&O technique chooses the maximum extracts of power based on the position movement. When the percentage of alteration in voltage source to modify in current is positive, then there is a small increment.

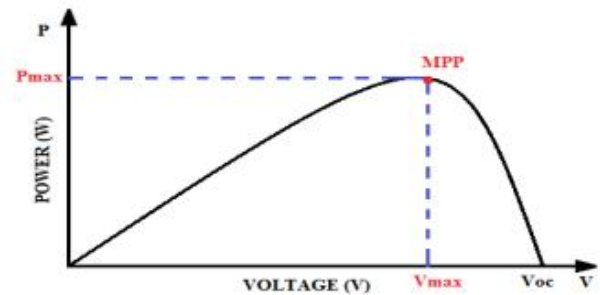


Fig.2 P-V characteristics of PV array system

If the proportion of modify in voltage to adjust in current is less than zero, then the large increment will occur at the same position of tracking also change. By observance the solar irradiation and temperature as constant to take out the maximum power from the projected system and the value of PV voltage, current & power can be determined. The PV array systems I-V characteristics of are shown in Fig 3.

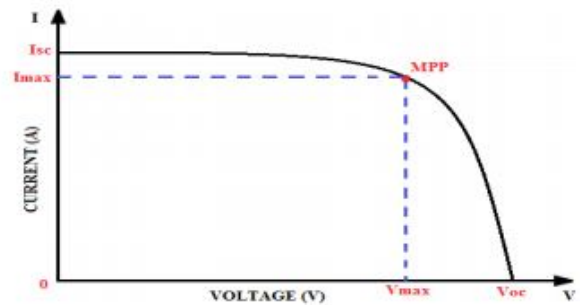


Fig.3 I-V characteristics of PV array system

**3.1 Variation in Temperature and solar radiation**

The conventional MPPT process can track in incorrect direction due to the changes occur in temperature and solar irradiations. And solar irradiations can change moderately faster corresponding to a variation of the rated power from 0% to 100% ranges within very small period of

time in very small PV systems. But the chance of such fast solar radiation changes is tremendously very low. The PV system with variation of solar radiation of I-V characteristics are shown in Fig 4.

If the changes in the temperature and solar radiations cause a greater revolutionize in power source than the one reason by the growth in the voltage value, the MPPT could acquire perplexed, as it will understand the revolutionize in the power source as an outcome of its own exploit. The conventional MPPT algorithm cannot read the direction of tracking the maximum power and voltage at the time variation occur in the temperature and solar radiations.

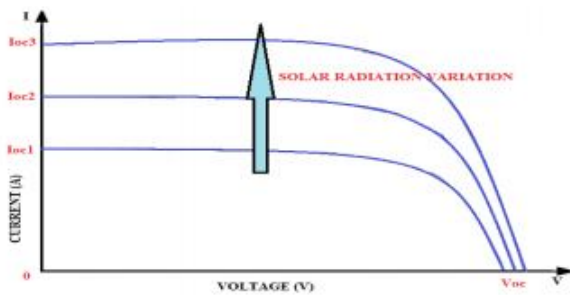


Fig. 4 I-V characteristics of PV system with variation of solar radiation

The PV system with variation of temperature of I-V characteristics are shown in Fig 5.

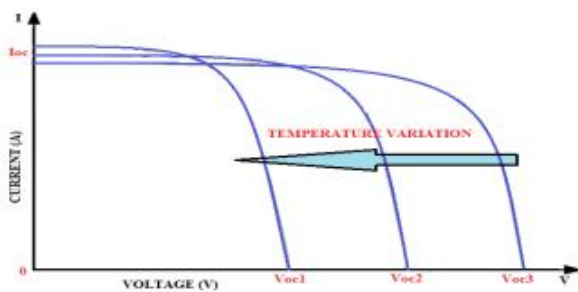


Fig. 5 I-V characteristics of PV system with variation of Temperature

**IV.FUZZY LOGIC CONTROLLER**

Our main idea is to combine Perturb and Observe (P&O) method in a one input fuzzy logic controller, in order to take into account the direction of variation of perturbation is shown in Fig 6. The input of fuzzy logic controller is a derivative of  $dP/dV$  and the output is different between the current duty cycle and the previous duty cycle  $\Delta D$  of boost converter DC/DC.

The rules table easily enables action on the control surface. If we choose a high value of output  $\Delta D$ , we can quickly achieve the PPM. But it leads us above the point of

maximum power (PPM). This also causes oscillations around the PPM. On the contrary, if we choose a small value of output  $\Delta D$ , the response time of our fuzzy logic controller is slow. But, we can easily reach the PPM. To solve this problem, we used thirteen membership functions of input  $dP/dV$ , and thirteen constant values of output  $\Delta D$ . The PPM was quickly reached, but was not exceeded. There were no oscillations anymore.

When the operating point was far to the left hand side of the PPM, the value of  $dP/dV$  was very positive; the duty cycle was shortened rapidly to increase the voltage toward the PPM.

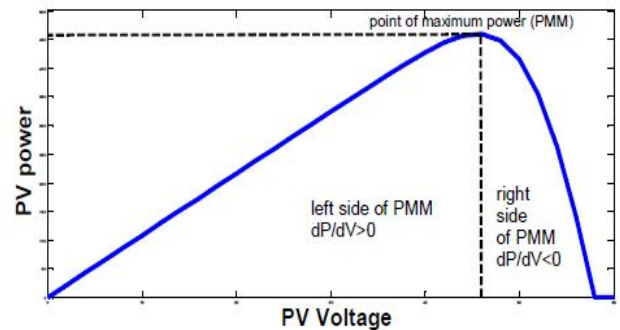


Fig.6 Description of the P&O method

When the operating point was close to the left hand side of the PPM, the value of  $dP/dV$  was positive but small, the duty cycle slowly decreased. When the operating point was the PPM, the value of  $dP/dV$  was zero, the duty cycle was kept constant, and there are no longer an oscillation anymore around the PPM is shown in Fig 7. There are three mains advantages to this method. By using only one input  $dP/dV$ , the structure of the proposed MPPT controller is simple.

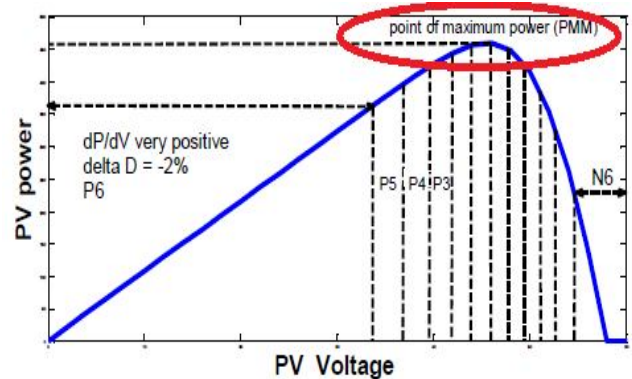


Fig.7 Description of the proposed method

The value of input  $dP/dV$  converges exactly to zero. And, it depends on the position of the operating point (near or far from the PPM): if it is near the value of output  $\Delta D$  is small,

if it is far the value of output  $\Delta D$  is big. This improves the response time compared to using the traditional method P&O.

After the derivative  $dP/dV$  is calculated, it is converted into thirteen linguistic variables  $dP/dV = \{N6, N5, N4, N3, N2, N1, Z, P1, P2, P3, P4, P5, P6\}$ . The domain of the input  $dP/dV$  is set to be  $[-1; 1]$ . A coefficient  $k$  will be used to adapt to each level power of panel PV. The output  $\Delta D$  was generated by thirteen value constants  $\Delta D = \{+2\%, +0.2\%, +0.1\%, +0.01\%, +0.006\%, +0.005\%, 0\%, -0.005\%, -0.006\%, -0.01\%, -0.1\%, -0.2\%, -2\%\}$ .

## V. RESULT AND DISSCUSSION

In order to verify the feasibility of our controller, insolation was modified, a resistive load  $100 \Omega$  was fixed, and another resistive load  $100 \Omega$  was switched. We tested our one input fuzzy logic controller in a number of cases during a long period of 25 seconds, and during a short period. In this case, we chosen  $N_s=3$ ,  $N_p=12$ . The coefficient  $k$  of MPPT controller was  $1/9$ . The maximum power of PV panel at  $900 \text{ W/m}^2$  was  $459.5 \text{ W}$ . During a long period of 25 seconds, the insolation variation and load variation are varied and to verify the response of the proposed MPPT fuzzy logic controller.

During the first five seconds, the insolation was  $800 \text{ W/m}^2$  (the optimal voltage of PV panel was  $V_{opt} = 46.1 \text{ V}$ , the maximum power of PV panel was  $P_{max} = 410.1 \text{ W}$ ). Our MPPT controller increased voltage of PV panel ( $V_{pv}$ ) from zero to  $V_{opt}$  that enabled maximum power extraction. It needed 0.2 seconds for our system to reach permanent regime. When the insolation was changed, there were small oscillations of  $dP/dV$  value from  $-0.3$  to  $0.3$  during 0.5 seconds. This leads a small oscillation of PV panel power. After 0.5 seconds, the  $dP/dV$  value was controlled to zero. The operating point was reached exactly to the PPM. It proved the accuracy of our controller.

When the insolation was changed from  $800 \text{ W/m}^2$  to  $300 \text{ W/m}^2$  (from 5th second to 10th second), our MPPT controller decrease  $V_{pv}$  to  $45.5 \text{ V}$  to extract the maximum power. We found the same phenomenon under different insolation variation (increased de  $300 \text{ W/m}^2$  to  $900 \text{ W/m}^2$ , then down to  $400 \text{ W/m}^2$ , then increased to  $700 \text{ W/m}^2$ ). We noted that  $V_{pv}$  always followed the  $V_{opt}$  for each level of the insolation. Under a load variation at 3rd second, a load variation and an insolation variation at the same time 5th second, we noted that our controller always managed to keep  $V_{pv}$  around its optimal value. The duty cycle  $D$  of boost converter was changed to extract the maximum power. After reaching the PPM, the duty cycle was kept constant. So, there was not power oscillation around PPM. It proved the proper

operating of our MPPT controller under the load variation and the insolation variation is shown in Fig 8.

At 5th, 10th, 15th, 20th, 25th second, when the insolation was changed, there were significant oscillations of the duty cycle  $D$  and of the input  $dP/dV$ . But, there were only small oscillations of PV panel power and PV panel voltage. It proved the stability of our controllers.

The simulations showed good results in terms of performance, robustness and flexibility of our MPPT controller. It always followed the PPM under variation of atmospheric condition and of the load. Under the rapid insolation variation, the simulations results show the power curve of PV panel, from 0.3s to 5s and from 0.2s to 5s, the power extracted is 99.9% of the maximal power. In this case, we chosen  $N_s=20$ ,  $N_p=30$ . The coefficient  $k$  of MPPT controller was  $1/20$ .

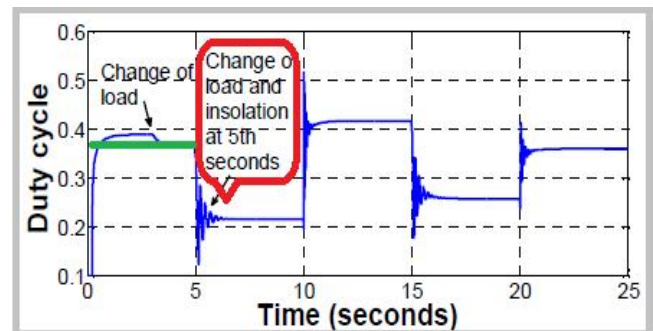


Fig.8 Duty cycle of boost converter

The same way in the PV system of small power, the simulation results in Fig. 9 show our MPPT controller operates very well under the variation of atmospheric condition and load in the PV system of high power.

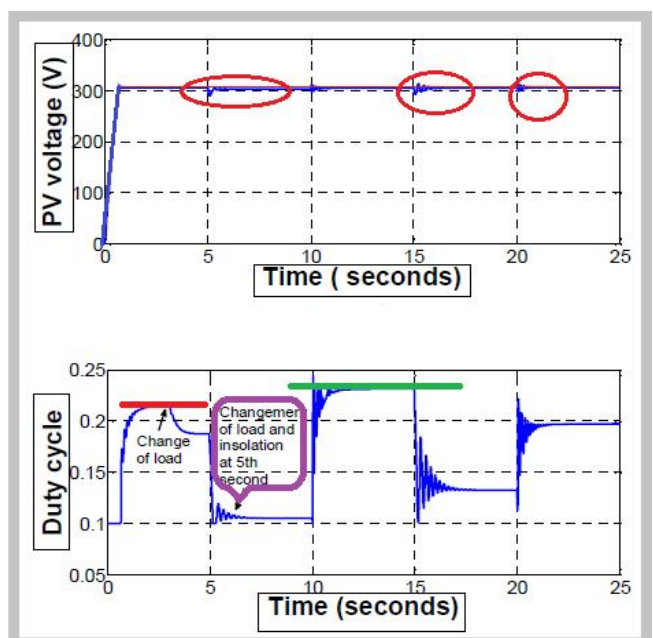


Fig.9 Voltage of PV panel and duty cycle of boost converter

To compare between one input MPPT fuzzy logic controller and two input ones. A simulation was performed with the same PV panel and the same resistive load during 50 seconds. The parameters of the proposed MPPT fuzzy logic controller were used in this paper. The simulation type is continuous. The two input ones were used. The simulation type was discrete, while there is a variation in insolation and load, one input MPPT fuzzy logic controller works with a faster response time, more accurate, and more stable than two input ones.

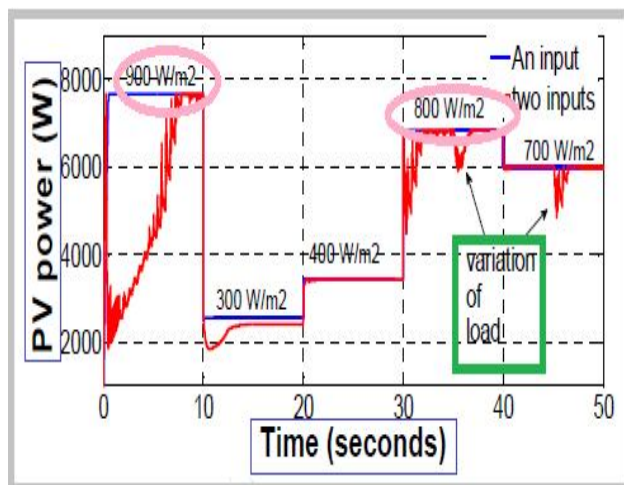


Fig.10 Power of PV panel

When the operating point reaches the PPM, there is any more oscillation in case of the one input MPPT. But, there is still a small oscillation in case of the two inputs MPPT as shown in Fig 10. In this simulation, we can conclude that one input MPPT fuzzy logic controller is better than two input ones in terms of performance, robustness and flexibility.

## VI. CONCLUSION

In this paper, a new simple one input MPPT fuzzy logic controller is presented. By using only one input  $dP/dV$ , the structure of the proposed MPPT controller is simple. The value of input  $dP/dV$  converges exactly to zero. And, it depends on the position of the operating point and if it is near the value of output  $\Delta D$  is small, if it is far the value of output  $\Delta D$  is big. Simulation results clearly showed that the one input MPPT fuzzy logic controller operated with fast time response, no overshoot, low oscillation, and was more stable with noise in the PV system as compared with two inputs MPPT fuzzy controller. The proposed MPPT fuzzy logic controller also worked well at rapid insolation variations. Simulation results have shown that the proposed method outperforms the conventional method in terms of tracking performance under

several different irradiance conditions, including various patterns for fuzzy logic.

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